

Department of Electronics Engineering

IIT (ISM), Dhanbad

Course Name- Computer Communication Lab

Course Code- ECC508

Location- 6th Floor Academic Complex

Experiment List

| Sr. No. | Name of Experiment | Page No. |
|---------|--|----------|
| 1. | Study of ALOHA protocol and Observe its throughput using MATLAB | 2-4 |
| 2. | Study of CSMA protocol and Observe its throughput using MATLAB | 5-11 |
| 3. | Study about different types of Line coding schemes | 12-19 |
| 4. | Perform the following: (a) Cable crimping (b) Standard Cabling (c) Cross Cabling (d) IO connector crimping (e) Testing the crimped cable using a cable tester | 20-28 |
| 5. | Implementation of Star topology and observation of packet transmission using Stop and Wait protocol | 29-36 |
| 6. | Study of Spanning tree and Prim's Algorithm | 37-40 |
| 7. | Study of Dijkstra shortest path Algorithm | 41-48 |
| 8. | Study of Spanning tress and Kruskal's Algorithm | 49-53 |

EXPERIMENT – 01

AIM: -

Study of ALOHA protocol.

Software Used: -

MATLAB

THEORY: -

ALOHA provides a wireless data network. It is a multiple access protocol (this protocol is for allocating a multiple access channel). There are two main versions of ALOHA: pure and slotted.

Pure ALOHA: The Original ALOHA protocol is called pure ALOHA. The idea is that each station sends a frame whenever it has a frame to send. Sender finds out whether transmission was successful or experienced a collision by listening to the broadcast from the destination station. If there is a collision, sender retransmits the frame after some random time.

Throughput:

Throughput for pure ALOHA is given as:

$$S = G * \exp(-2*G)$$

The maximum throughput $S_{max} = 0.184$

When $G = (1/2)$

Here, $G =$ avg. no. of frames generated by the system

Slotted ALOHA: In Slotted ALOHA, time is divided up into discrete intervals, each interval corresponding to one frame. A station is required to wait for the beginning of the next time slot in order to send the next packet, if a station misses this moment, it must wait until the beginning of the next time slot.

Throughput:

Throughput for slotted ALOHA is given as:

$$S = G * \exp(-G)$$

The maximum throughput $S_{max} = 0.368$ when

$G = 1$ Here, $G =$ avg. no. of frames generated by

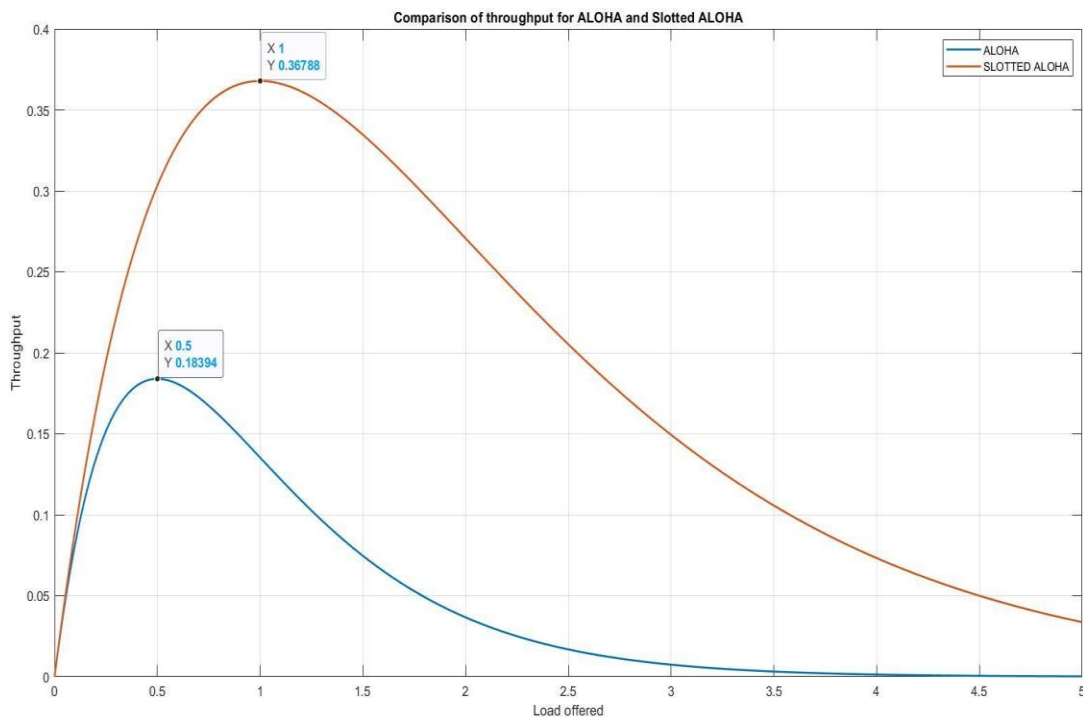
the system

MATLAB CODE:-

```

clc
clear all
closeall
G=0:0.01:10;
TPPA=G.* exp(-2*G);
%TPPA=ThroughPut of Pure Aloha
figure(1)
plot(G,TPPA)
hold on
TPSA=G.* exp(-G);
plot(G,TPSA)
%TPSA=ThroughPut of Slotted Aloha
title('Study of ALOHA Protocol')
xlabel('G(Avg No. of Frames Sent in One Frame Time)')
ylabel('Throughput (S)')
legend ('Pure ALOHA','Slotted ALOHA')
grid on
grid

```

OUTPUT :

EXPERIMENT:-2

AIM: -

Study of CSMA protocol.

Software used: -

MATLAB 2019 A

Theory:-

Carrier-sense multiple access (CSMA) is a media access control (MAC) protocol in which a node verifies the absence of other traffic before transmitting on a shared transmission medium, such as an electrical bus or a band of the electromagnetic spectrum. CSMA is based on the principle “sense before transmit”. CSMA can reduce the possibility of collision, but it cannot eliminate it.

There are mainly three theoretical versions of the CSMA protocol:

1-Persistent: 1-persistent CSMA is an aggressive transmission algorithm. When the transmitting node is ready to transmit, it senses the transmission medium for idle or busy. If idle, then it transmits immediately. If busy, then it senses the transmission medium continuously until it becomes idle, then transmits the message (a frame) unconditionally (i.e. with probability=1). In case of a collision, the sender waits for a random period of time and attempts the same procedure again. 1-persistent CSMA is used in CSMA/CD systems including Ethernet.

Non-persistent: Non-persistent CSMA is a non-aggressive transmission algorithm. When the transmitting node is ready to transmit data, it senses the transmission medium for idle or busy. If idle, then it transmits immediately. If busy, then it waits for a random period of time (during which it does not sense the transmission medium) before repeating the whole logic cycle (which started with sensing the transmission medium for idle or busy) again. This approach reduces collision, results in overall higher medium throughput but with a penalty of longer initial delay compared to 1-persistent.

P-persistent: This is an approach between 1-persistent and non-persistent CSMA access modes. [1] When the transmitting node is ready to transmit data, it senses the transmission medium for idle or busy. If idle, then it transmits immediately. If busy, then it senses the transmission medium continuously until it becomes idle, then transmits with probability p . If the node does not transmit (the probability of this event is $1-p$), it waits until the next available time slot. If the transmission medium is not busy, it transmits again with the same probability p . This probabilistic hold-off repeats until the frame is finally transmitted or when the medium is found to become busy again (i.e. some other node

has already started transmitting). In the latter case the node repeats the whole logic cycle (which started with sensing the transmission medium for idle or busy) again. P-persistent CSMA is used in CSMA/CA systems including Wi-Fi and other packet radio systems.

CSMA/CD: CSMA/CD is used to improve CSMA performance by terminating transmission as soon as a collision is detected, thus shortening the time required before a retry can be attempted. CSMA/CD is used by Ethernet.

CSMA/CA: In this method, collisions are avoided through the use of three strategies: Inter-frame space (IFS), the contention window and acknowledgements.

When an idle channel is found, the station does not send immediately. It waits for a period of time called the IFS. The contention window is an amount of time divided into slots. A station that is ready to send chooses a random number of slots as its wait time. This is very similar to the p-persistent method.

Unslottednon-persistent:

$$\text{ThroughputS} = G \cdot \exp(-a \cdot T) / (G \cdot (1 + 2a) + \exp(-a \cdot G))$$

Unslotted1-persistent:

$$\text{ThroughputS} = G(1 + G + aG(1 + G + aG/2)) \cdot \exp(G(1 + 2a)) / (G(1 + 2a) - (1 - \exp(aG)) + (1 + aG) \exp(-G(1 + a)))$$

Slottednon-persistent:

$$\text{ThroughputS} = a \cdot G \cdot \exp(-a \cdot T) / (1 + a - \exp(-a \cdot G))$$

Slotted1-persistent:

$$\text{ThroughputS} = G(1 + a - \exp(-aG)) \cdot \exp(-G(1 + a)) / ((1 + a)(1 - \exp(-aG)) + a \cdot \exp(-G(1 + a)))$$

Matlabcode:

```
clc;clear
```

```
all;close
```

```
all;
```

```
G=0.001:.001:1000;
```

```
a=[0 .001 .01 .1
```

```
1];T=1;
```

```
figure(1);f
```

```
ori=1:1:5
```

```
Sn=G*T.*exp(- a(i)*G*T) ./ (G*T*(1+2*a(i))+exp(-
```

```
a(i)*G*T));semilogx(G,Sn);
```

```
holdon;
```

```
endlegend('a=0','a=.001','a=.01','a=.1','a=1')
```

```
;
```

```
title('unslotted non-
```

```
persistant');figure(2);
```

```
fori=1:1:5
```

```
Sn=G*T.*exp(-G*T*(1+2*a(i)).*(1+G*T+G*a(i)*T.*(1+G*T+G*a(i)*T/2))...
```

```
./ (G*T*(1+2*a(i))-(1-exp(-a(i)*G*T))+ (1+G*a(i)*T).*exp(-G*T*(1+a(i)))));%unslotted 1
```

```
persistantsemilogx(G,Sn);
```

```
holdon;
```

```
endlegend('a=0','a=.001','a=.01','a=.1','a=1')
```

```
;
```

```
title('unslotted 1-
```

```
persistant');figure(3);
```

```
fori=1:1:5
```

```
Sn=a(i)*G*T.*exp(-a(i)*G*T)./(1-exp(-a(i)*G*T)+a(i)*T);%slottednonpersiscta
```



```

semilogx(G,Sn);
hold on;

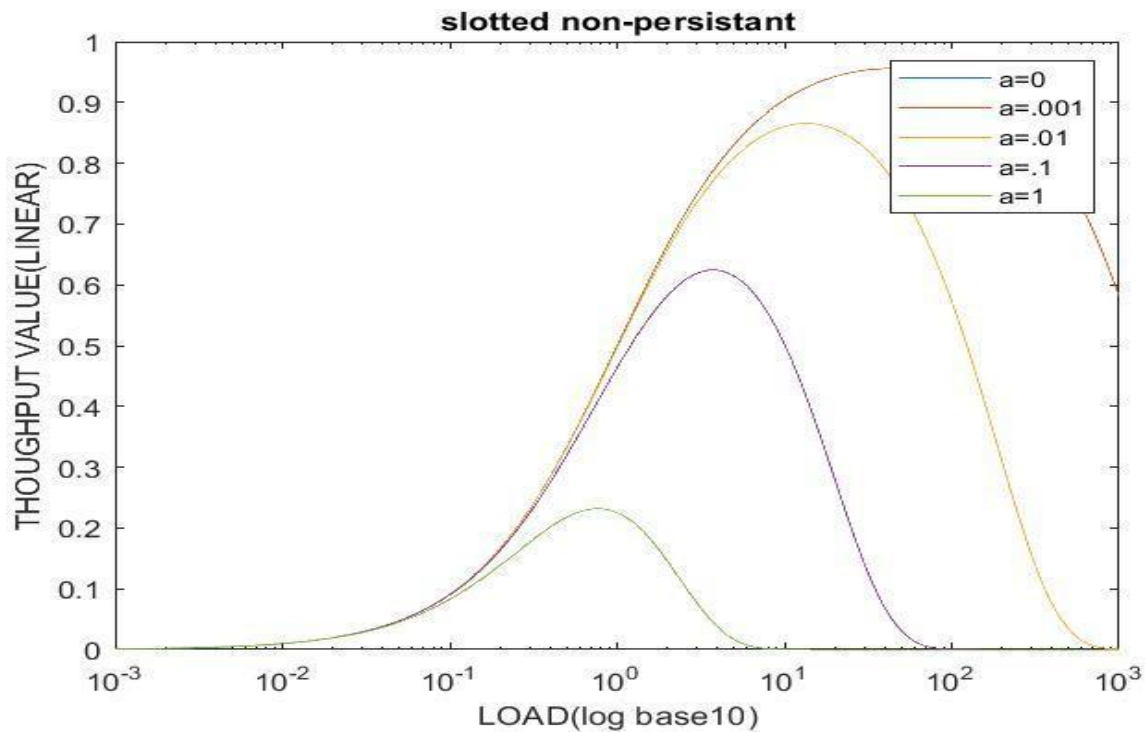
endlegend('a=0','a=.001','a=.01','a=.1','a=1')
;
title('slotted non-
persistant');figure(4);
for i=1:1:5

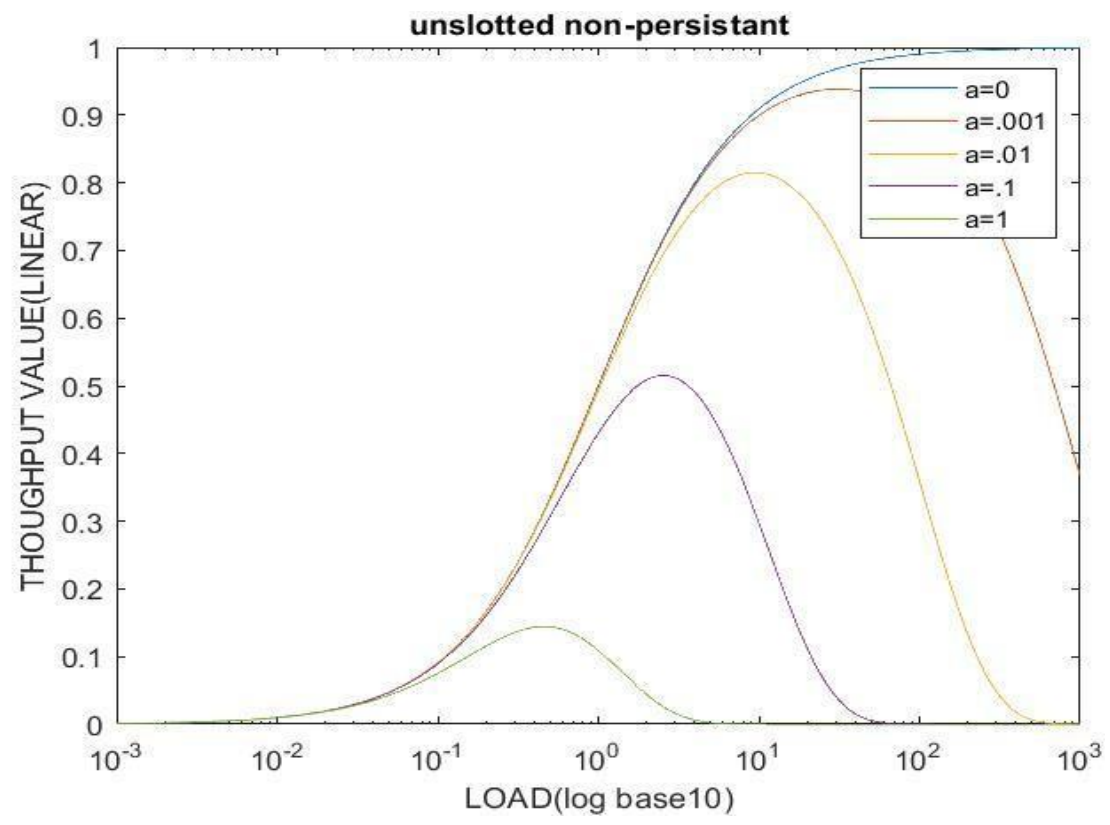
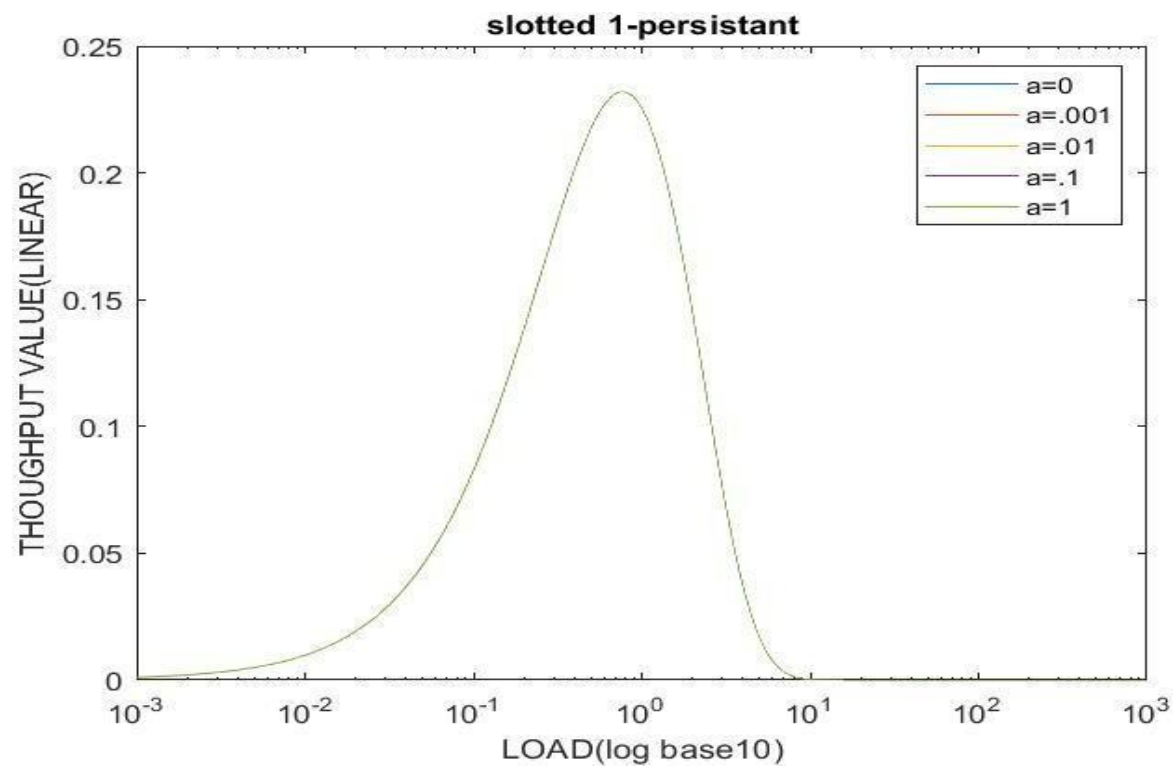
S_s1p=G*T.*exp(-G*T*(1+a(i))).*(1+a(i)-exp(-a(i)*G*T))...
./ ((1+a(i))*(1-exp(-a(i)*G*T))+a(i).*exp(-G*T*(1+a(i))));%slotted 1
persisctantsemilogx(G,Sn);
hold on;

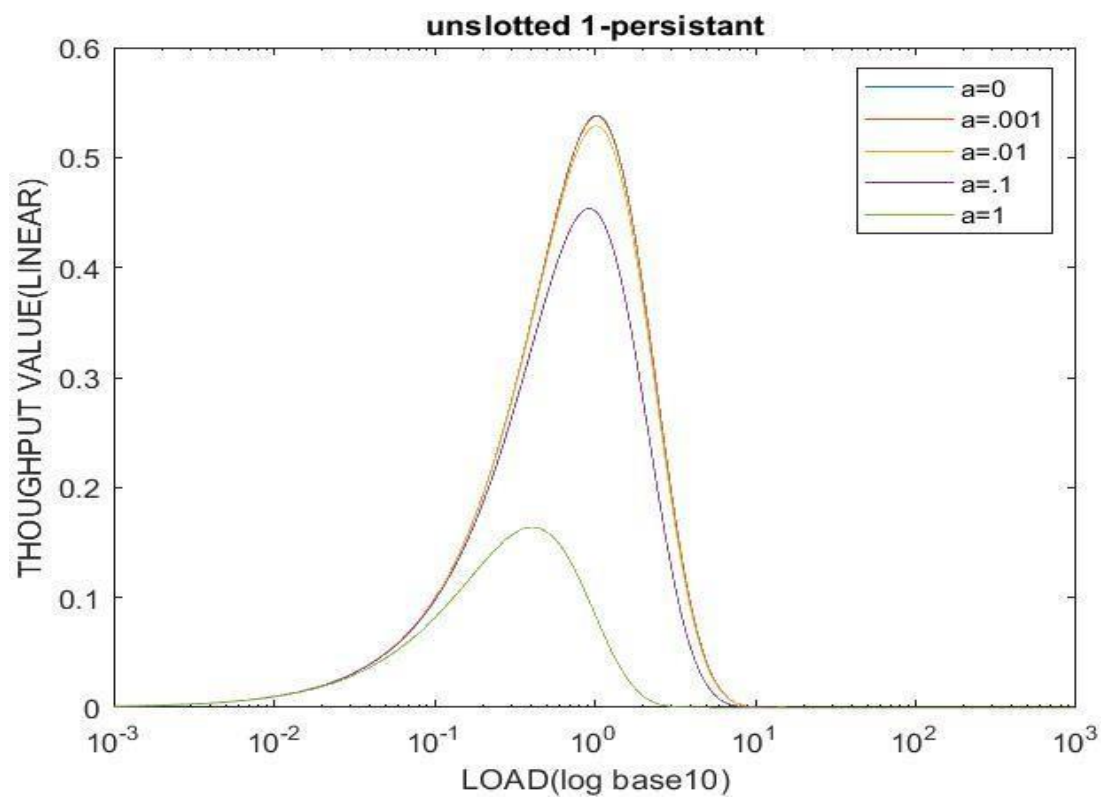
endlegend('a=0','a=.001','a=.01','a=.1','a=1')
;
title('slotted1-persistent');

```

Output:







EXPERIMENTNO:-3

OBJECTIVE:-TostudydifferentLineCodingSchemes

SOFTWAREUSED:-MATLAB2018b

THEORY:-

A line code is the code used for data transmission of a digital signal over a transmissionline. This process of coding is chosen so as to avoid overlap and distortion of signals such as inter-symbol interference.

Differenttypesoflinecodingschemesare:-

- Polar NRZ code :-"One" is represented by one positive level (A volts), while"zero" is representedbynegativelevel ($-A$ volts).
- Manchester code :-Manchester code always has a transition at the middle ofeach bit period and may have a transition at the start of the period also. Thedirection of the mid-bit transition indicates the data. Transitions at the periodboundaries do not carry information. They exist only to place the signal in thecorrectstate to allowthemid-bit transition.
- Alternate Mark Inversion(AMI) code :- AMI is a bipolar encoding systemwhereneutral(zero)voltage representsbinary 0andalternating positiveandnegative voltages represents binary 1. With this line encoding it is the alternatingvoltagesthatdetermines the binayones.
- Pseudo ternarycode:- ThisencodingschemeissameasAMI,butalternatingpositiveandnegativepulsesoccurfor binary0 insteadof binary1.
- 2B1Q code :-It is a four-level pulse amplitude modulation (PAM-4) schemewithoutredundancy,mappingtwobits(2B)intoonequaternarysymbol(1Q).

MATLABCODE:-

```

clc;
closeall;c
learall;
x=[10010011 01];
N=length(x);
m=[];
y1=[];
y2=[];
y3=[];
y4=[];
y5=[];
count1=0;
count2=0;
check=0;f
ori=1:N
    ifx(i)==1
        m=[mones(1,100)];
        y1=[y1ones(1,100)];
        y2=[y2ones(1,50)];
        y2=[y2 -
ones(1,50)];ifrem(cou
nt1,2)==0
            y3=[y3ones(1,50)];
            y3=[y3
zeros(1,50)];count1=
count1+1;
        else
            y3=[y3-ones(1,50)];
            y3=[y3zeros(1,50)];c
ount1=count1+1;
        end
        y4=[y4
zeros(1,100)];ifcheck
==0
            check=1;
        elseifcheck==-1
            y5=[y5-
3*ones(1,200)];check=0;
        else
            y5=[y5

```

```
3*ones(1,200) ] ; check=0;
```

```

        end
    end
else
    m=[mzeros(1,100)];
    y1=[y1-ones(1,100)];
    y2=[y2-ones(1,50)];
    y2=[y2
ones(1,50)];y3=[y3
zeros(1,100)];ifrem(c
ount2,2)==0
        y4=[y4
ones(1,100)];count2=
count2+1;
    else
        y4=[y4-
ones(1,100)];count2=c
ount2+1;
    end
    ifcheck==0
        check=-
1;elseifcheck==-1
        y5=[y5-
ones(1,200)];check=0;
    else
        y5=[y5
ones(1,200)];check=0;
    end
end
end
end

end
t=0:1/100:10-1/100;
subplot(321)plot(t,m,'LineWid
th',2)
title({'LineCodingSchemes','x-axis:Time(inseconds)
','y-
axis:Amplitude(inVolts)','Binarybits'})gridon
gridminorsub
plot(322)
plot(t,y1,'LineWidth',2)
title('Polar NRZ
Code')gridon

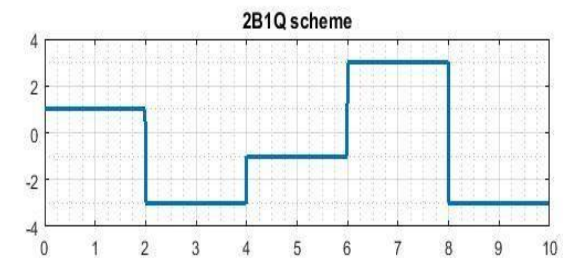
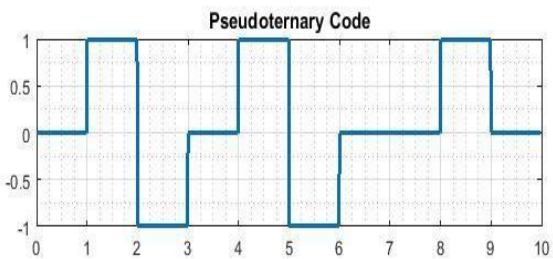
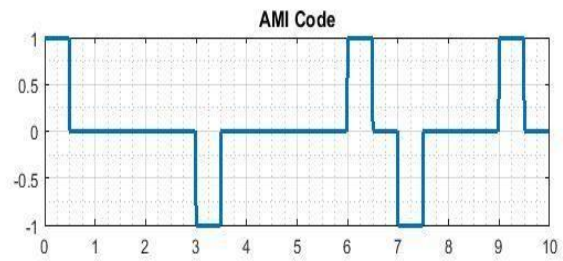
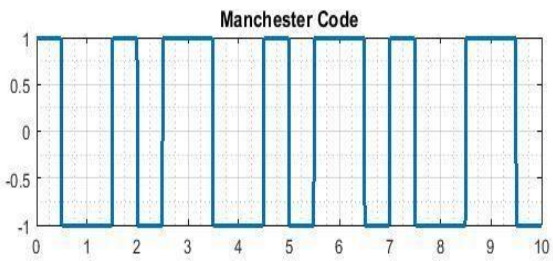
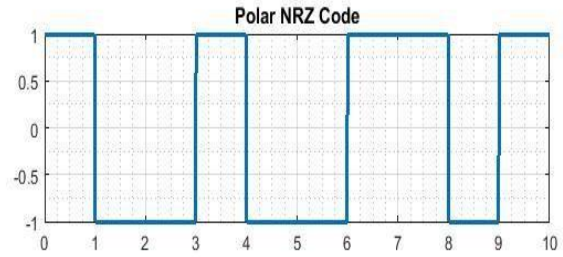
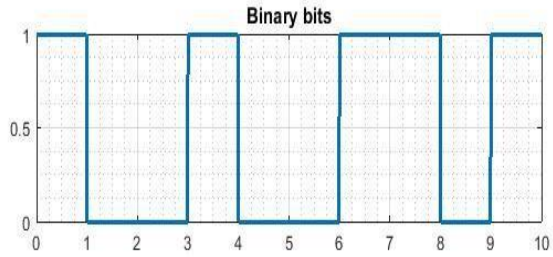
```

gridminor


```
subplot(323)plot(t,y2,'LineWidth',2)title('ManchesterCode')gridon
gridminorsub
plot(324)
plot(t,y3,'LineWidth',2)title('AMICode')
gridongrid
minor
subplot(325)plot(t,y4,'LineWidth',2)title('PseudoternaryCode')gridon
gridminorsub
plot(326)
plot(t,y5,'LineWidth',2)
title('2B1Qscheme')gridon
gridminor
```

OUTPUT:-**Line Coding Schemes**

x-axis: Time (in seconds) , y-axis: Amplitude (in Volts)



CONCLUSION:-

- Implementation of various line coding techniques using Matlab is observed by taking 10 bits.
- In Manchester code, we have observed that
 - 1 is represented by +1 volt for first $T_b/2$ duration and -1 volt for the next $T_b/2$ duration
 - While 0 is represented by -1 volt for first $T_b/2$ duration and +1 volt for the next $T_b/2$ duration
- In 2B1Q scheme, we have observed that 1st bit of the pair decides polarity while 2nd bit of the pair decides the magnitude.

In our code 1 as 1st bit represent + and 0 as 1st bit represent,

While 1 as 2nd bit represent a magnitude of 3 and 0 as 2nd bit represent a magnitude of 1

So therefore, 11 represents +3 volts

10 represents +1 volt

00 represents -1

volt 01 represents -3 volts

EXPERIMENT:-4

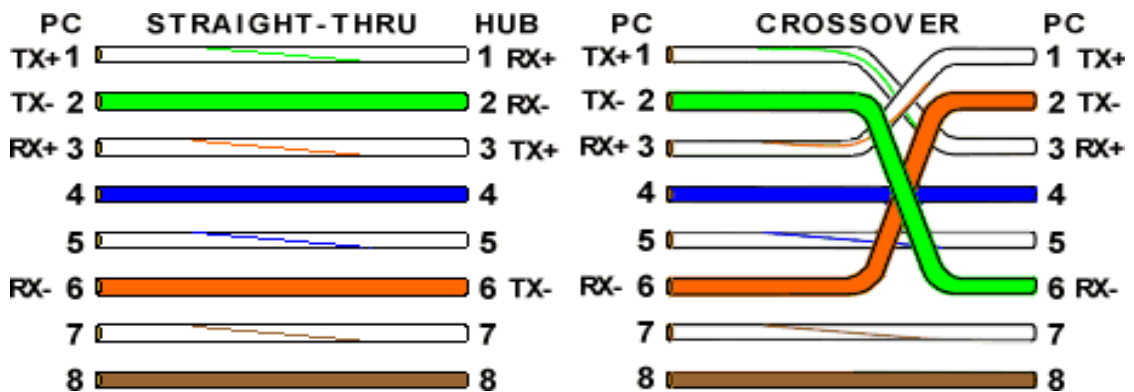
AIM: -

Perform the following:

- a. Cable crimping
- b. Standard Cabling
- c. Cross Cabling
- d. IO connector crimping
- e. Testing the crimped cable using a cable tester

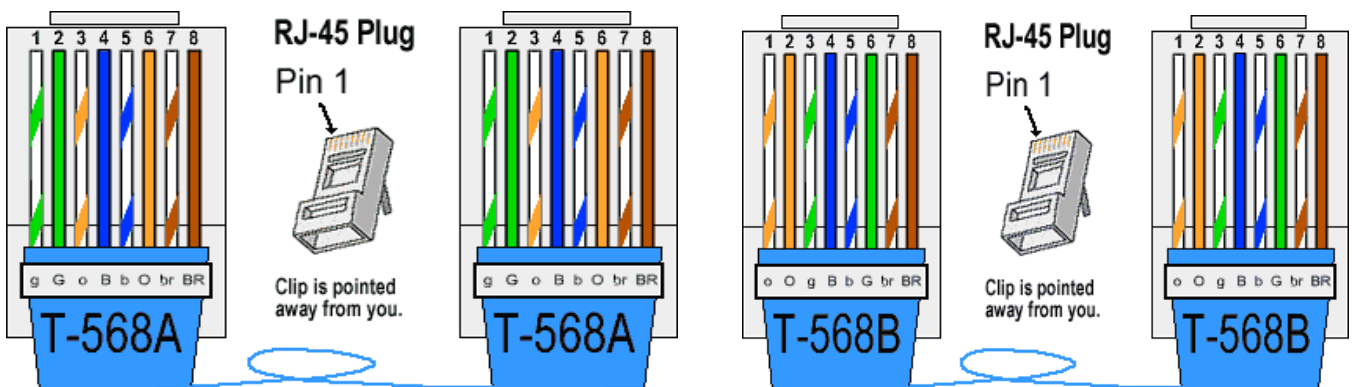
THEORY: -

Nowadays Ethernet is a most common networking standard for LAN (local area network) communication. The Ethernet cable used to wire a RJ45 connector of network interface card to a hub, switch or network outlet. The cable is called patch cord, straight-thru cable.



By looking at a T-568A UTP Ethernet straight-thru cable and an Ethernet crossover cable with a T-568B end, we see that the TX (transmitter) pins are connected to the corresponding RX (receiver) pins, plus to plus and minus to minus. We can also see that both the blue and brown wire pairs on pins 4, 5, 7, and 8 are not used in either standard.

T-568A/B Straight-Through Ethernet Cable

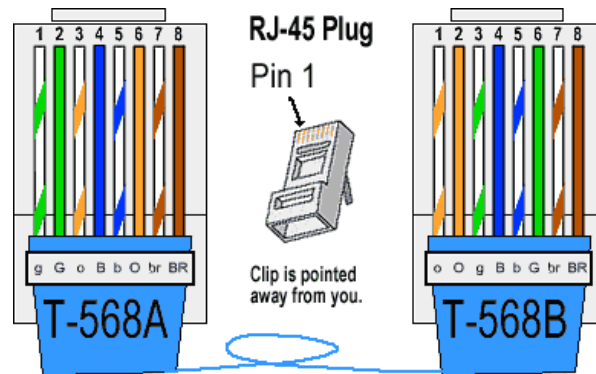


The TIA/EIA 568-A standard which was ratified in 1995, was replaced by the TIA/EIA 568-B standard in 2002 and has been updated since. Both standards define the T-568A and T-568B pin-

outs for using Unshielded Twisted Pair cable and RJ-45 connectors for Ethernet connectivity. The standards as and pin-outs specification appear to be related and interchangeable, but are not the same and should not be used interchangeably.

Both the T-568A and the T-568B standard Straight-Through cables are used most often as patch cords for your Ethernet connections. If you require a cable to connect two Ethernet devices directly together without a hub or when you connect two hubs together, you will need to use a Crossover cable instead.

RJ-45 Crossover Ethernet Cable



A good way of remembering how to wire a Crossover Ethernet cable is to wire one end using the T-568A standard and the other end using the T-568B standard. Another way of remembering the color coding is to simply switch the Green set of wires in place with the Orange set of wires. Specifically, switch the solid Green (G) with the solid Orange, and switch the green/white with the orange/white.

Requirement:

Ethernet Cable - bulk Category (Cat) 5, 5e, 6, 6a or higher
 Ethernet cable Wire Cutters-to
 cut and strip the Ethernet cable if necessary

For Patch Cables:

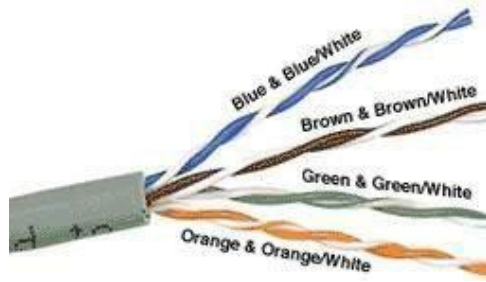
8P8C Modular Connector Plugs
 ("RJ45") Modular Connector Crimper
 ("RJ45") 110 Punch Down Tool

Recommended:

Wire
 Stripper/Cable
 Tester

About the Cable: We can find bulk supplies of Ethernet cable at many computer stores or most electrical or home centers. We want UTP (Unshielded Twisted Pair) Ethernet cable of at least Category 5 (Cat 5). Cat 5 is required for basic 10/100 functionality, we will want Cat 5e for gigabit (1000BaseT) operation and Cat 6 or higher gives a measure of future proofing. We can also use STP (Shielded Twisted Pair) for extra resistance to external interference but we won't cover shielded connectors. Bulk Ethernet cable comes in many types; there are 2 basic categories, solid and braided stranded cable. Stranded Ethernet cable tends to work better in patch applications for desktop use. It is more flexible and resilient than solid Ethernet cable and easier to work with, but really meant for shorter lengths. Solid Ethernet cable is meant for longer runs in a fixed position. Plenum-rated Ethernet cable must be used whenever the cable travels through an air circulation space. For example, above a false ceiling or below a raised floor. It may be difficult or impossible to tell from the package or labeling what type of Ethernet cable it is, so peel out an end and investigate.

Here is what the internal of the Ethernet cable look like:



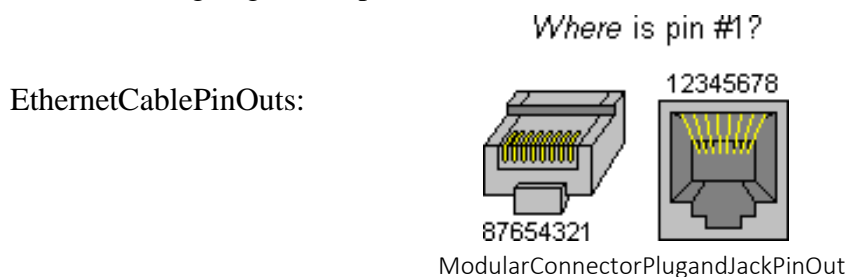
Inside the Ethernet cable, there are 8 color coded wires. These wires are twisted into 4 pairs of wires, each pair has a common color theme. One wire in the pair being a solid or primarily solid colored wire and the other being a primarily white wire with a colored stripe (Sometimes Ethernet cables won't have any color on the striped wire, the only way to tell which is which is to check which wire it is twisted around). The twists are extremely important. They are there to counteract noise and interference. It is important to wire according to a standard to get proper performance from the Ethernet cable. The TIA/EIA-568-A specifies two wiring standards for an 8-position modular connector such as RJ45. The two wiring standards, T568A and T568B vary only in the arrangement of the coloured pairs.

About Modular Connector Plugs and Jacks:

The 8P8C modular connectors for Ethernet are often called RJ45 due to their physical resemblance. The plug is an 8-position modular connector that looks like a large phone plug. There are a couple variations available. The primary variation you need to pay attention to is whether the connector is intended for braided or solid wire. For braided/stranded wires, the connector has sharp pointed contacts that actually pierce the wire. For solid wires, the connector has fingers which cut through the insulation and make contact with the wire by grasping it from both sides.

Modular connector jacks come in a variety of styles intended for several different mounting options. The choice is one of requirements and preference. Jacks are designed to work only with solid Ethernet cable. Most jacks come labeled with color coded wiring diagrams either for T568A, T568B or both.

Here is a wiring diagram and pinout:



There are two basic Ethernet cable pin outs. A straight through Ethernet cable, which is used to connect to a hub or switch, and a crossover Ethernet cable used to operate in a peer-to-peer fashion without a hub/switch. Generally, all fixed wirings should be run as straight through.

How to wire Ethernet Patch Cables:

- Strip off about 2 inches of the Ethernet cable sheath.
- Untwist the pairs - don't untwist them beyond what you have exposed, the more untwisted cable you have the worse the problems you can run into.
- Align the colored wires according to the wiring diagrams above.
- Trim all the wires to the same length, about 1/2" to 3/4" left exposed from the sheath.
- Insert the wires into the RJ45 plug - make sure each wire is fully inserted to the front of the RJ45 plug and in the correct order. The sheath of the Ethernet cable should extend into the plug by about 1/2" and will be held in place by the crimp.

- Crimp the RJ45 plug with the crimper tool.
- Verify the wires ended up the right order and that the wires extend to the front of the RJ45 plug and make good contact with the metal contacts in the RJ45 plug

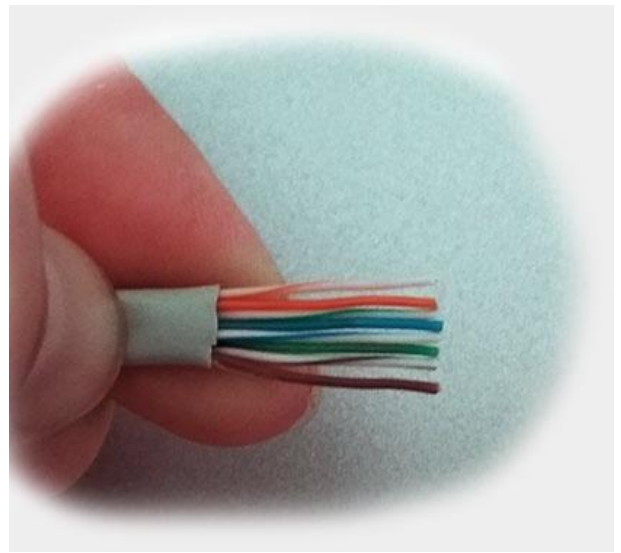
- Cut the Ethernet cable to length - make sure it is more than long enough for your needs.
- Repeat the above steps for the second RJ45 plug.

PROCEDURE:

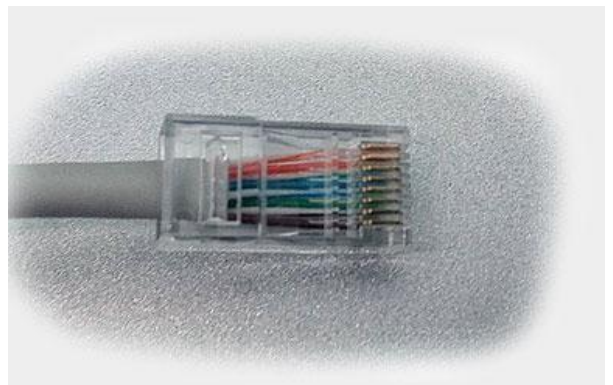
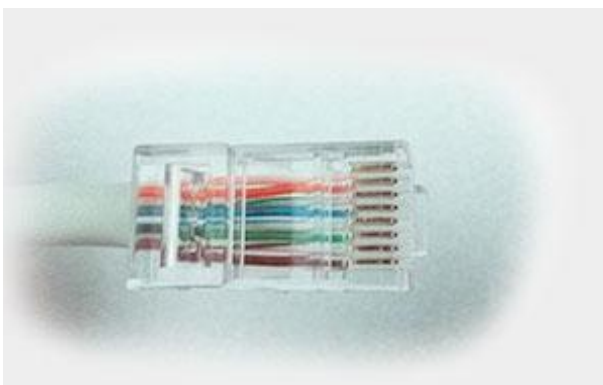
Pull the cable off the reel to the desired length and cut. The total length of wire segments between a PC and a hub or between two PC's cannot exceed 100 Meters (328 feet) for 100BASE-TX and 300 Meters for 10BASE-T.

Start on one end and strip the cable jacket off (about 1") using a stripper or a knife. Be extra careful not to nick the wires, otherwise we will need to start over.

Spread, untwist the pairs, and arrange the wires in the order of the desired cable end. Flatten the end between thumb and forefinger. Trim the ends of the wires so they are even with one another, leaving only $1/2''$ in wire length. If it is longer than $1/2''$ it will be out-of-spec and susceptible to crosstalk. Flatten and insure there are no spaces between wires.



Hold the RJ-45 plug with the clip facing down or away from you. Push the wires firmly into the plug. Inspect each wire is flat even at the front of the plug. Check the order of the wires. Double check again. Check that the jacket is fitted right against the stop of the plug. Carefully hold the wire and firmly crimp the RJ-45 with the crimper.



Check the color orientation, check that the crimped connection is not about to come apart, and check to see if the wires are flat against the front of the plug. If even one of these are incorrect, we will have to start over. Test the Ethernet cable using a tester

Ethernet Cable Tips:

- A straight-thru cable has identical ends.
- A crossover cable has different ends.
- A straight-thru is used as a patch cord in Ethernet connections.
- A crossover is used to connect two Ethernet devices without a hub or for connecting two hubs.
- A crossover has one end with the Orange set of wires switched with the Green set.
- Odd numbered pins are always striped, even numbered pins are always solid coloured.
- Looking at the RJ-45 with the clip facing away from you, Brown is always on the right, and pin 1 is on the left.
- No more than 1/2" of the Ethernet cables should be untwisted otherwise it will be susceptible to crosstalk.
- Do not deform, do not bend, do not stretch, do not staple, do not run parallel with power cables, and do not run Ethernet cables near noise inducing components.

EXPERIMENTNO:- 5**AIM: -**

Implementation of star topology and observation of packet transmission using stop and wait protocol.

SOFTWARE/PACKAGEUSED:-

MATLAB(R2020a)

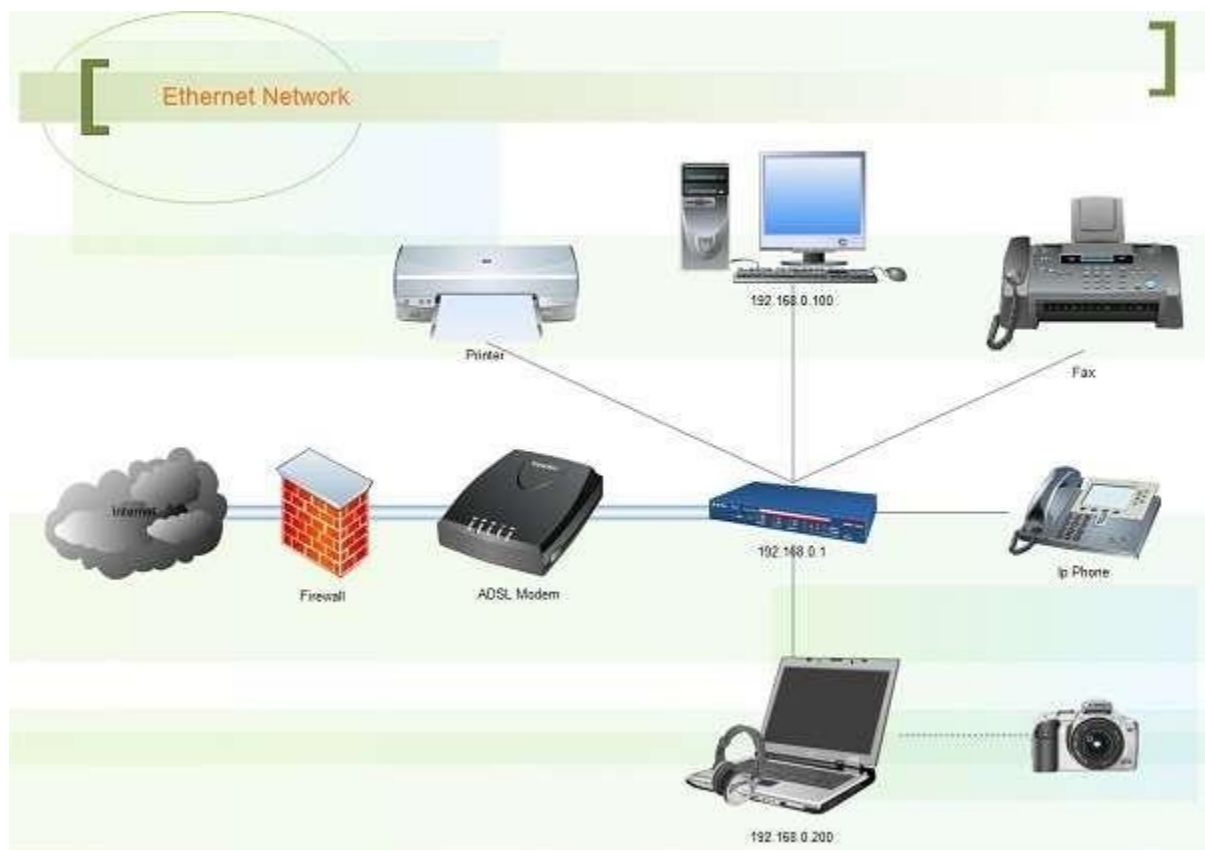
THEORY:-

- Originally known as **Alto Aloha Network**, **Ethernet** is a widely used **LAN** (local area network) **protocol** created at Xerox PARC in 1973 by Robert Metcalfe and others.
- Being the first network to provide Carrier Sense Multiple Access / Collision Detection (CSMA/CD), Ethernet is a fast and reliable network solution that is still widely used today.
- **Ethernet** is the technology that is commonly used in wired **local areanetworks(LANs)**.
- A **LAN** is a network of computers and other electronic devices that covers a small area such as a room, office, or building. It is used in contrast to a **wideareanetwork(WAN)**, which spans a large geographical area.
- Ethernet is a network protocol that controls how data is transmitted over a LAN and is referred to as the IEEE 802.3 protocol. The protocol has evolved and improved over time to transfer data at the speed of more than a gigabit per second.
- **Ethernet** connects computers together with cable so the computers can share information. Within each main branch of the network, "**Ethernet**" can connect up to 1,024 personal computers and workstations.
- **Ethernet** provides services on the **Physical Layer** (Layer 1) and **Data Link Layer** (Layer 2) of the OSI reference model.
- The Data Link Layer is further divided into two sub layers that are Logical Link Control (LLC) and Media Access Control (MAC), these sub layers can be used to establish the transmission paths and format data before transmitting on the same network segment.
- Systems that use Ethernet communication divide their data into packets, which are also known as frames.

- These frames further contain source and destination address, a mechanism which was used to detect errors in the data and retransmission requests.

Wired Ethernet:

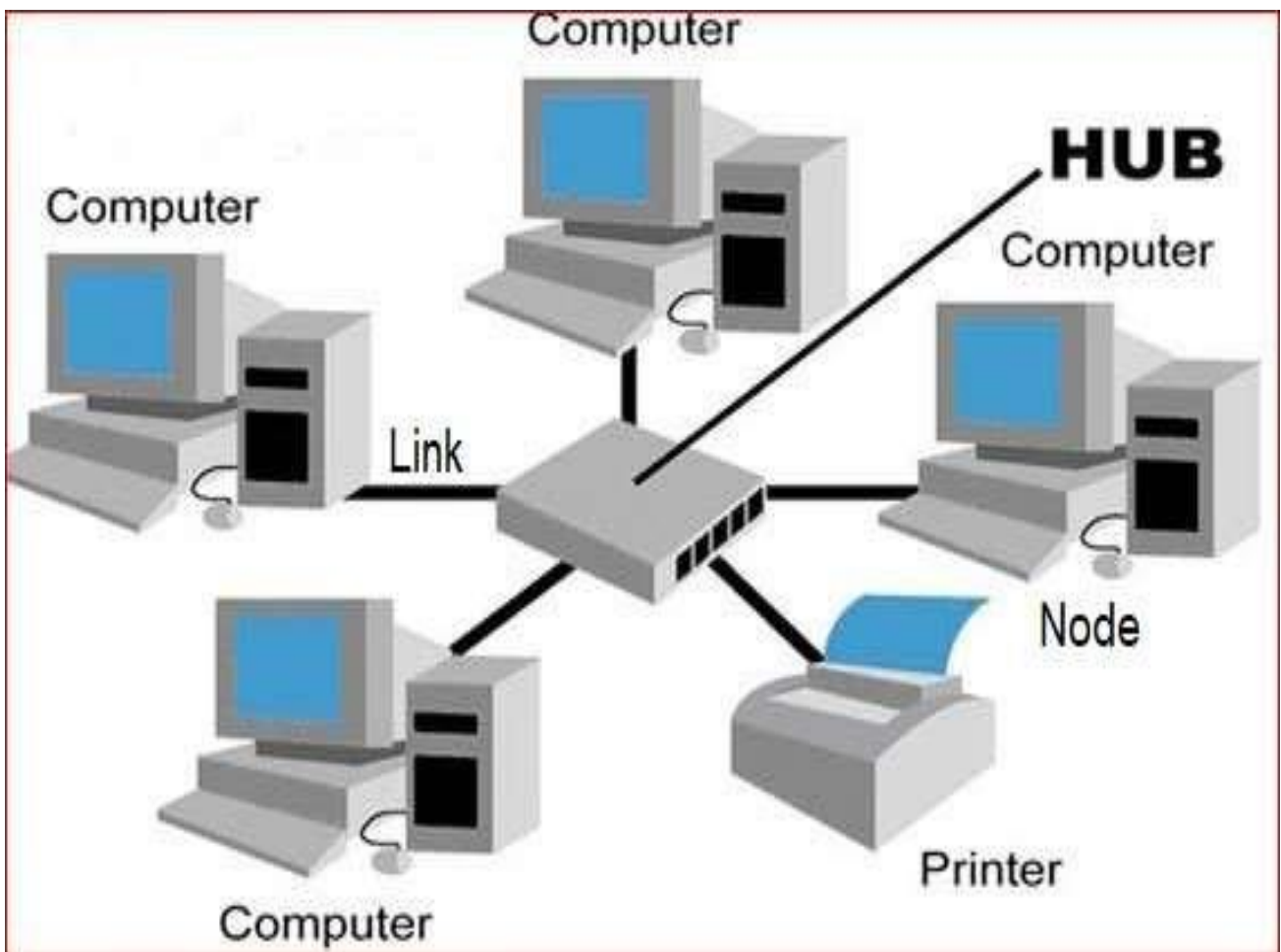
- Ethernet can be designed to run over coaxial cables, twisted pair cables, fiber optic cable.
- In Wired Ethernet network, devices are connected with the help of a CAT cable or fiber optic cable, which connects the devices within a distance of 10 km in case of fiber optic cable and 90 m in case of CAT cable.
- For this, we have to install a computer network interface card (NIC) in each computer. A unique address is given to each computer that is connected.
- So, for sharing data and resources like printers, computers, and other machines, Ethernet networking is used as it establishes a communications system.
- Ethernet is a shared medium network technology, where all the workstations are connected to the same cable and must connect with one another to send signals over it.



Wired Ethernet Network

StarTopology:

- In **Star Topology**, all the Nodes are connected to the centrally located network device or node, like a hub, switch, router, or computer.
- All the devices on the network are connected with a Hub through a communication link. Each computer requires a single wire for the connection to the Hub.
- In **Star Topology**, there exists a point-to-point connection between a node and Hub. The Hub takes a signal from any node and passes it to all the other nodes in the network. The hub works as a server and it controls and manages entire function of the network.
- If one host needs to send data to some other host, it will send the message to the central connecting Hub. The central connecting Hub then replicates the message and forwards it to the appropriate host.
- Depending on the network card used in each computer of the *star topology*, a RJ-45 network cable or a coaxial cable is used to connect computers together.



StarTopology

Advantages of Star Topology:

- Centralized management of the network, through the use of the central computer, hub, or switch.
- Easy to add another computer to the network and No disruptions to the network when connecting or removing devices.
- If one computer on the network fails, the rest of the network continues to function normally.
- Easy fault detection because the links are often easily identified.
- Each device requires just one port i.e., to attach to the hub.
- If N devices are connected to every other in star, then the number of cables required to attach them is N. So, it's easy to line up.

Disadvantages of Star Topology:

- May have a higher cost to implement, especially when using a switch or router as the central network device.
- The central network device determines the performance and number of nodes the network can handle.
- If the central computer, hub, or switch fails, the entire network goes down and all computers are disconnected from the network.
- Hub requires more resources and regular maintenance because it's the central system of star Topology.

PING Command:

- **PING (Packet Internet Groper)** command is used to check the network connectivity between host and server/host i.e., it is a Command Prompt command used to test the ability of the source computer to reach a specified destination computer.
- It is usually used as a simple way to verify that a computer can communicate over the network with another computer or network device.
- This command takes as input the IP address or the URL and sends a data packet to the specified address with the message "PING" and get a response from the server/host this time is recorded which is called latency.
- Ping operates by sending Internet Control Message Protocol (ICMP) echo request packets to the target host and waiting for an ICMP echo reply.

Stop and Wait Protocol:

- It is a data-link layer protocol which is used for transmitting the data over the noiseless channels.
- It provides unidirectional data transmission which means that either sending or receiving of data will take place at a time.
- It provides flow-control mechanism but does not provide any error control mechanism.
- The idea behind the usage of this is that when the sender sends the frame then he waits for the acknowledgment before sending the next frame.

Primitives of Stop and Wait Protocol:

Sender Side:

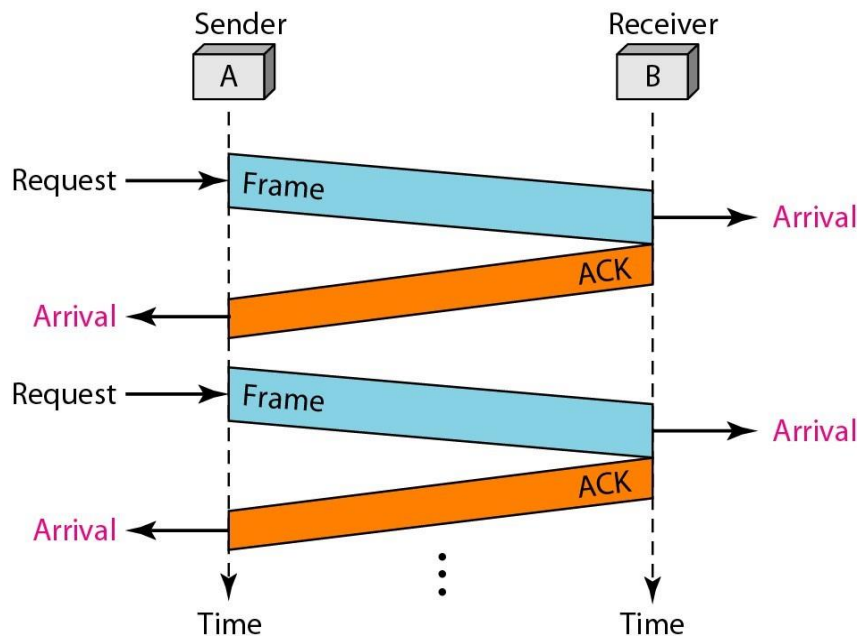
- ✓ **Rule 1:** Sender sends one data packet at a time.
- ✓ **Rule 2:** Sender sends the next packet only when it receives the acknowledgment of the previous packet.
- Therefore, the idea of stop and wait protocol in the sender's side is very simple, i.e., send one packet at a time, and do not send another packet before receiving the acknowledgment.

Receiver Side:

- ✓ **Rule 1:** Receive and then consume the data packet.
- ✓ **Rule 2:** When the data packet is consumed, receiver sends the acknowledgment to the sender.
- Therefore, the idea of stop and wait protocol in the receiver's side is also very simple, i.e., consume the packet, and once the packet is consumed, the acknowledgment is sent. This is known as a flow control mechanism.

Working of Stop and Wait Protocol:

- In this method of flow control, the sender sends a single frame to receiver & waits for an acknowledgment.
- The next frame is sent by sender only when acknowledgment of previous frame is received.
- This process of sending a frame & waiting for an acknowledgment continues as long as the sender has data to send.
- To end up the transmission sender transmits end of transmission (EOT) frame.



Flow Diagram of Stop and Wait Protocol

- The main advantage of stop & wait protocols is its accuracy. Next frame is transmitted only when the first frame is acknowledged. So, there is no chance of frame being lost.

Disadvantages of Stop and

✚ Wait Protocol: Problems due to lost data:

- Suppose the sender sends the data and the data is lost. The receiver is waiting for the data for a long time.
- Since the data is not received by the receiver, so it does not send any acknowledgment.
- Since the sender does not receive any acknowledgment so it will not send the next packet.



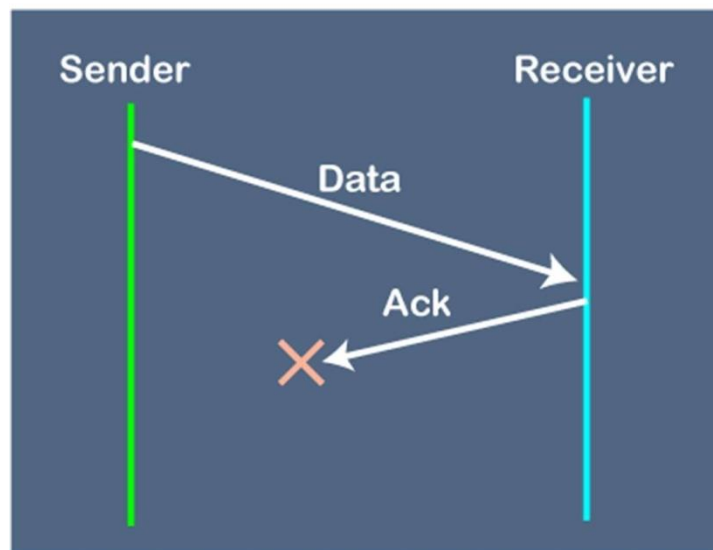
Problems due to lost data

- **In this case, two problems occur:**

- Sender waits for an infinite amount of time for an acknowledgment.
- Receiver waits for an infinite amount of time for data.

- **Problems due to lost acknowledgment:**

- Suppose the sender sends the data and it has also been received by the receiver. On receiving the packet, the receiver sends the acknowledgment.
- In this case, the acknowledgment is lost in a network, so there is no chance for the sender to receive the acknowledgment.
- There is also no chance for the sender to send the next packet as in stop and wait protocol, the next packet cannot be sent until the acknowledgment of the previous packet is received.



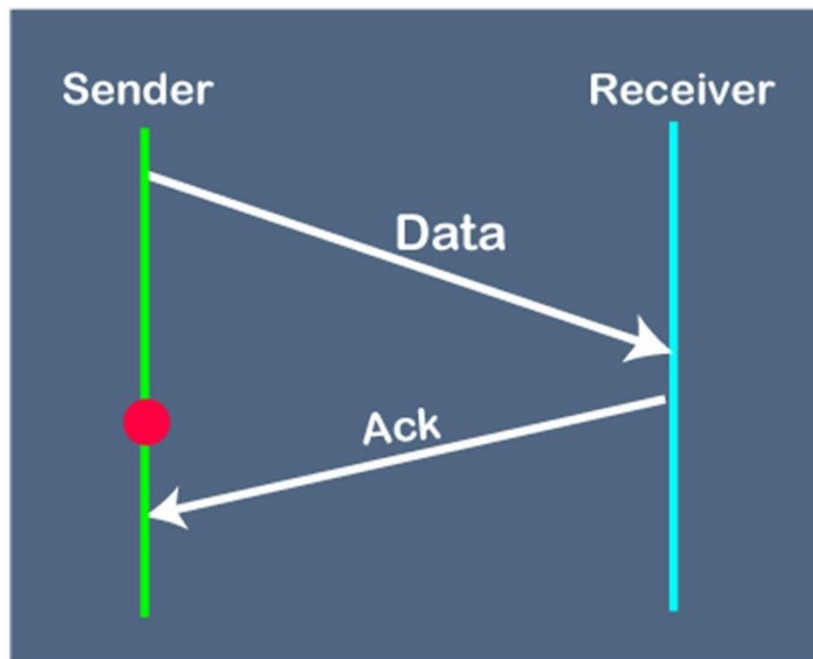
Problems due to lost acknowledgement

- **In this case, one problem occurs:**

- Sender waits for an infinite amount of time for an acknowledgment.

- **Problem due to the delayed data or acknowledgment:**

- Suppose the sender sends the data and it has also been received by the receiver.
- The receiver then sends the acknowledgment but the acknowledgment is received after the timeout period on the sender's side.
- As the acknowledgment is received late, so acknowledgment can be wrongly considered as the acknowledgment of some other data packet.



Problem due to the delayed data or acknowledgment

CONCLUSION:

- Steps involved in packet transmission using stop and wait protocol using Star Topology are studied.
- Star Topology has Central communicating device called HUB, which acts as a server and controls the data communication in that network. If it fails, then the entire network goes down.
- PING command is used to check the connectivity between devices in the Network.
- Here, Stop and wait protocol is used for transmission of data from one device to other. It is unidirectional data transmission protocol where data flows in only one direction.
- In this method of flow control, if sent data frame or Acknowledgment is lost, it may lead to infinite waiting time at sender or receiver. This can be resolved by using a timer at the sender side.

EXPERIMENT NO:- 6

AIM: -

Study of Spanning tree and Prim's Algorithm

Software Used: -

MATLAB

THEORY:-

The Spanning Tree Protocol is a network protocol that builds a loop-free logical topology for Ethernet networks. The basic function of STP is to prevent bridge loops and the broadcast radiation that results from them.

Configure Spanning Tree Protocol on SW1-SW4 so that:

1. Identify which Switch is Root Bridge?
2. Identify which Spanning Tree type is running on SW1 & SW2?
3. What is the STP role & state of Port Fa0/1 on SW4?
4. What is the STP role & state of Port Fa0/1 on SW2?
5. What is the STP role & state of Port Fa0/3 on SW3?
6. Interfaces, IP Addresses, GW & all other related detail is mentioned on the topology.

TOPOLOGY: Consider the following Lab Topology where multiple Switches are connected to each other through Trunk Links:

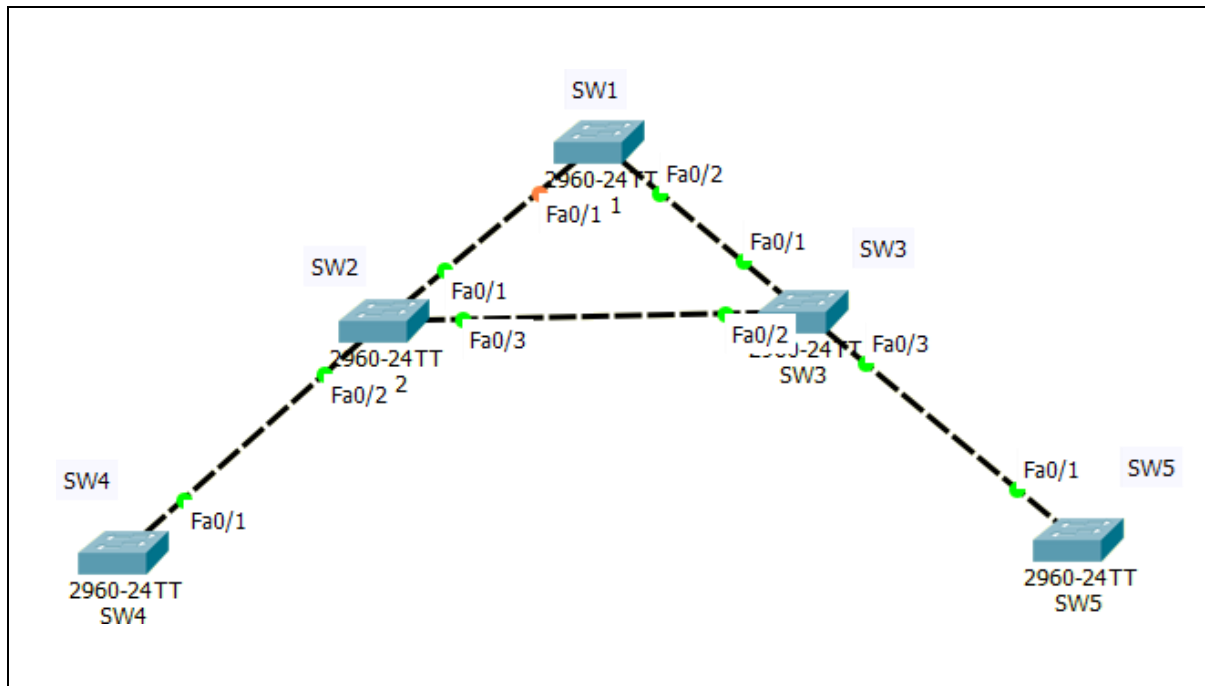


Fig: SpanningTreeProtocol

1-IdentifywhichSwitchisRootBridge?

SW5

```
Switch#show spanning-tree summarySwitch
is invst mode
Rootbridgefor:default
ExtendedsystemID          isenabled
PortfastDefault           is
disabledPortFast          BPDU      Guard
DefaultisdisabledPortfast BPDU Filter Default is
disabledLoopguardDefault  isdisabled
```

2-IdentifywhichSpanningTreetypeisrunningonSW1&SW2?

SW1

```
Switch#show spanning-tree summarySwitch
is invst mode
Rootbridgefor:
ExtendedsystemID          isenabled
PortfastDefault           is
disabledPortFast          BPDU      Guard
DefaultisdisabledPortfastBPDUFilterDefaultisdisabled
LoopguardDefault          is disabled
EtherChannelmisconfigguardis disabled
```

```
UplinkFast          is disabled
BackboneFast        is disabled
ConfiguredPathcostmethodused  isshort
```

| Name | Blocking | Listening | Learning | Forwarding | STP | Active |
|----------|----------|-----------|----------|------------|-----|--------|
| VLAN0001 | 1 | 0 | 0 | 1 | | 2 |

3-WhatistheSTProle&stateofPort Fa0/1onSW4?

```
SW4#show spanning-
treeVLAN0001
SpanningtreeenabledprotocolieeeRootID
Priority      32769
Address       0001.421A.D959
```

4-WhatistheSTProle&state ofPortFa0/1onSW2?

```
SW2#show spanning-
treeVLAN0001
SpanningtreeenabledprotocolieeeRootID
Priority      32769
Address       0001.421A.D959
Cost          38
Port          3(FastEthernet0/3)
HelloTime2secMaxAge20secForwardDelay15sec

BridgeIDPriority      32769(priority 32768 sys-id-ext 1)Address
                      0060.3E55.E404
HelloTime2secMaxAge20secForwardDelay15secAgingTime20
Interface      Role Sts Cost      Prio.Nbr Type
-----
Fa0/2          Desg FWD 19         128.2   P2p
Fa0/3          Root FWD 19         128.3   P2p
Fa0/1          Desg FWD 19         128.1   P2p
```

5-WhatistheSTProle&state ofPortFa0/3onSW3?

```
SW3#show spanning-
treeVLAN0001
SpanningtreeenabledprotocolieeeRootID
Priority      32769
Address       0001.421A.D959
Cost          19
Port          3(FastEthernet0/3)
HelloTime2secMaxAge20secForwardDelay15sec

BridgeIDPriority      32769(priority 32768 sys-id-ext 1)Address
```

0030.A3CA.4B33
HelloTime2secMaxAge20secForwardDelay15secAgingTime20

| Interface | RoleSts | Cost | Prio.Nbr | Type |
|-----------|---------|------|----------|------|
| Fa0/2 | DesgFWD | 19 | 128.2 | P2p |
| Fa0/3 | RootFWD | 19 | 128.3 | P2p |
| Fa0/1 | DesgFWD | 19 | 128.1 | P2p |

EXPERIMENT NO:-7

AIM: -

To study Dijkstra's Algorithm

SOFTWARE USED: -

Cisco Software

THEORY: -

Dijkstra's algorithm: is a solution to the single-source shortest path problem in graph theory.

Works on both directed and undirected graphs. However, all edges must have nonnegative weights.

Approach: Greedy

Input: Weighted graph $G = \{E, V\}$ and source vertex, such that all edge weights are nonnegative

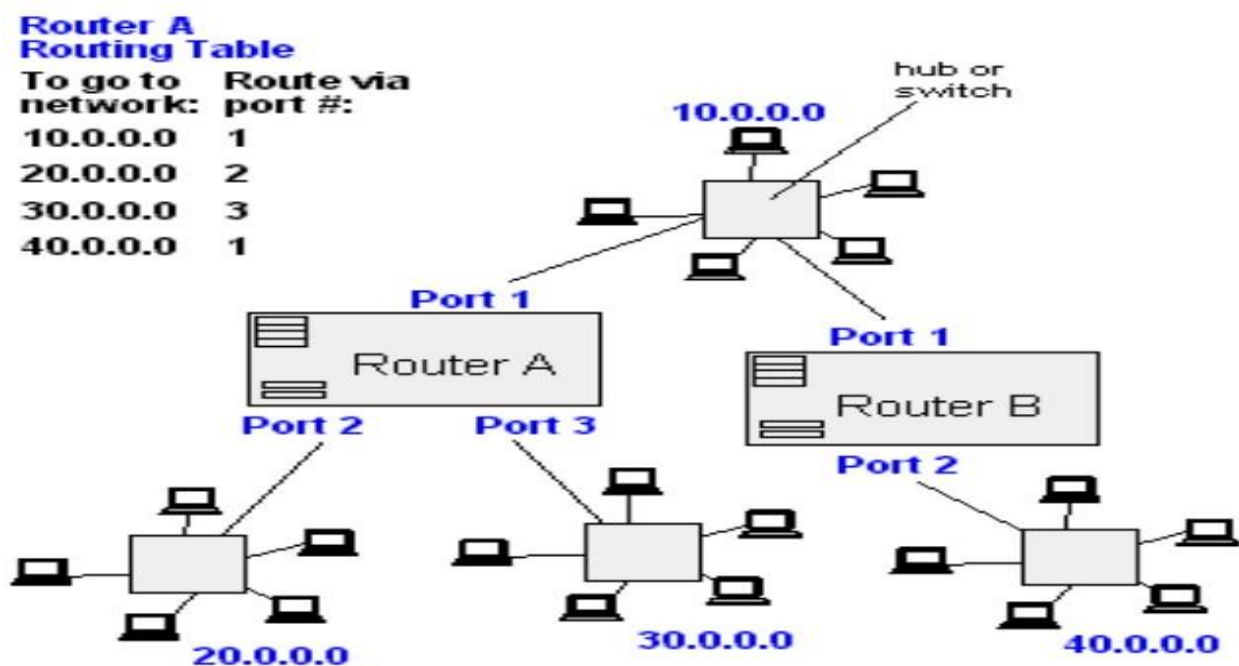
Output: Lengths of shortest paths (or the shortest paths themselves) from a given source vertex to all other vertices

DIJKSTRA'S ALGORITHM-WHY USE IT?

1-As mentioned, Dijkstra's algorithm calculates the shortest path to every vertex.

2-However, it is about as computationally expensive to calculate the shortest path from vertex u to every vertex using Dijkstra's as it is to calculate the shortest path to some particular vertex v .

3-Therefore, anytime we want to know the optimal path to some other vertex from a determined origin, we can use Dijkstra's algorithm.



RouteComputation

Routersasnodes

Ethernetcables/WIFISignal/Optical fiber edges

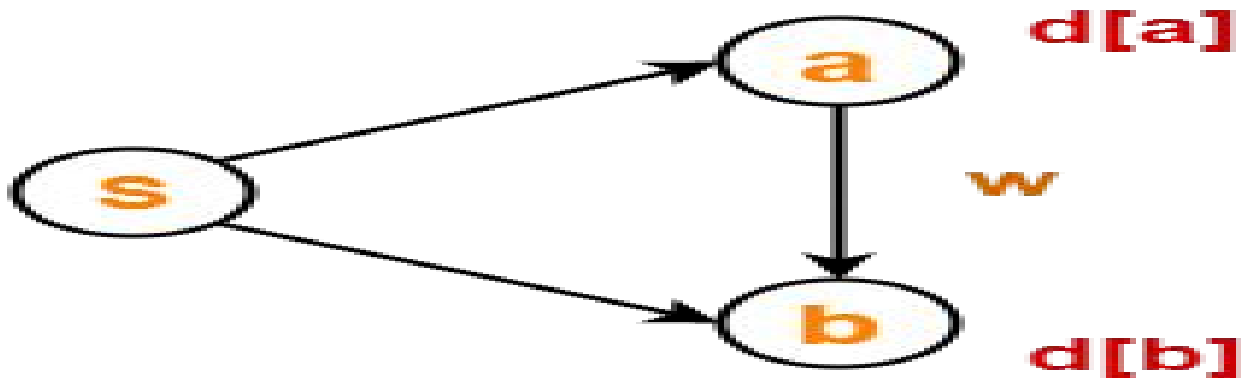
Computethepathfromonerouterto another.

Dijkstra'salgorithm-Pseudocode

```

dist[s] ← 0    (distancetosourcevertexiszero)forallv ∈ V - {s}
dodist[v] ← ∞ (setallotherdistancetoinfinity)
S ← ∅ (S,thesetofvisitedverticesisinitiallyempty)
Q ← V (Q,thequeueinitiallycontainsallvertices)
while Q ≠ ∅ (whilethequeueisnotempty)
do
    u ← mindistance(Q,dist)
        (selecttheelementofQwiththemin.distance) S ← S ∪ {u}    (addtolistofvisitedvertices)
for all v ∈ neighbors[u]
do if dist[v] > dist[u] + w(u,v) (if new shortest path found) then    d[v] ← dist[u] + w(u,v)
        (setnewvalueofshortestpath)
(ifdesired,addtracebackcode)returndist
  
```

What is Edge Relaxation?



Considertheedge(a,b)inthefollowinggraph-

Here, $d[a]$ and $d[b]$ denotestheshortestpathestimateforverticesaandbrespectivelyfromthesourcevertex 'S'.

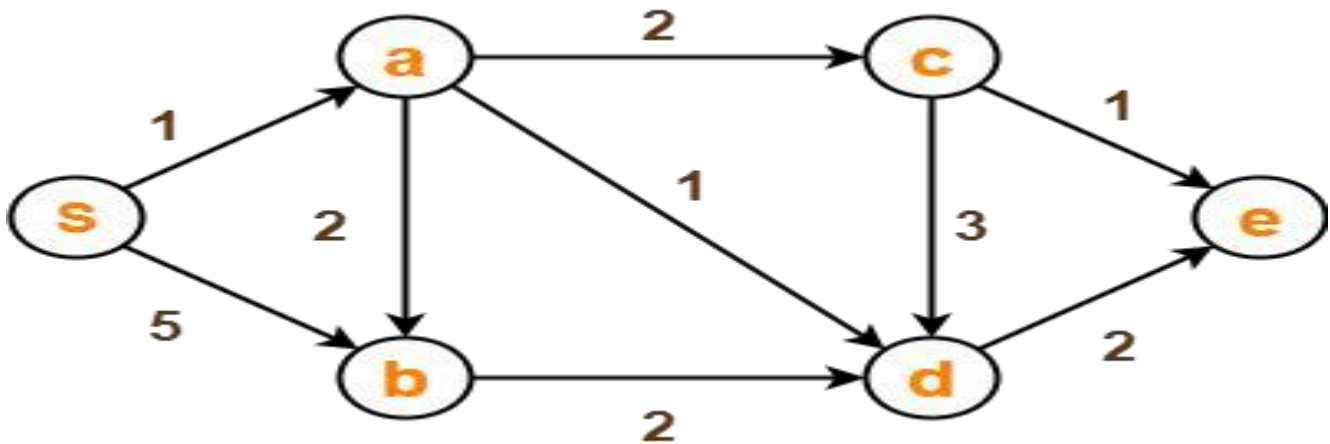
Now,

If $d[a] + w < d[b]$

thend $[b] = d[a] + w$ and $\Pi[b] = a$ Thisiscalledasedge relaxation.

Example:

Using Dijkstra's Algorithm, find the shortest distance from source vertex 'S' to remaining vertices in the following graph-



Also, write the order in which the vertices are revisited.

Step-01:

The following two sets are created-

Unvisited set: {S, a, b, c, d, e}

Visited set: {}

Step-02:

The two variables Π and d are created for each vertex and initialized as-

$\Pi[S] = \Pi[a] = \Pi[b] = \Pi[c] = \Pi[d] = \Pi[e] = \text{NIL}$

$d[S] = 0$

$d[a] = d[b] = d[c] = d[d] = d[e] = \infty$

Step-03:

Vertex 'S' is chosen.

This is because shortest path estimate for vertex 'S' is least.

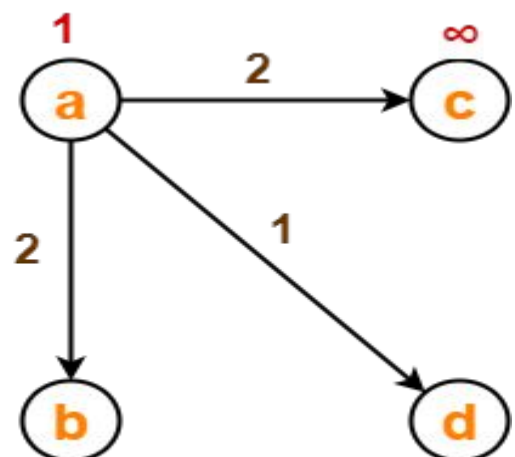
The outgoing edges of vertex 'S' are relaxed.

Step-04:

Vertex 'a' is chosen.

This is because shortest path estimates for vertex 'a' is least.

The outgoing edges of vertex 'a' are relaxed.

Before Edge Relaxation

Now,

$$d[a]+2=1+2=3 < \infty$$

$$\therefore d[c] = 3 \text{ and } \Pi[c]=a$$

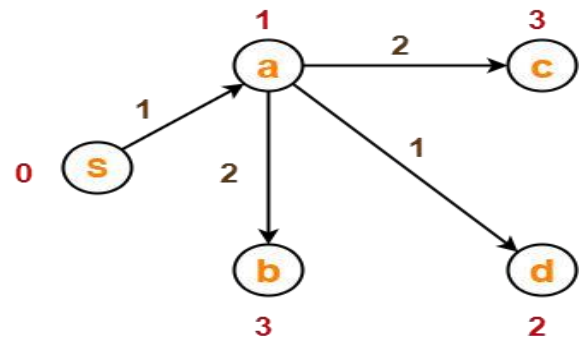
$$d[a]+1=1+1=2 < \infty$$

$$\therefore d[d] = 2 \text{ and } \Pi[d]=a$$

$$d[b]+2=1+2=3 < 5$$

$$\therefore d[b] = 3 \text{ and } \Pi[b]=a$$

After edge relaxation, our shortest path tree is-



Now, the sets are updated as-

Unvisited set: {b, c, d, e}

Visited set: {s, a}

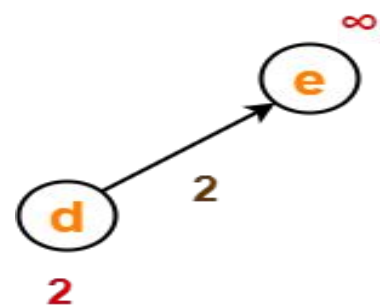
Step-05:

Before Edge Relaxation-

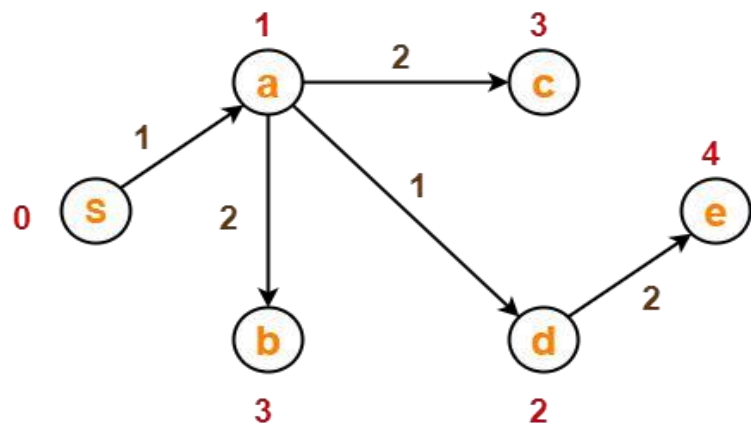
Now,

$$d[d]+2=2+2=4 < \infty$$

$$\therefore d[e] = 4 \text{ and } \Pi[e]=d$$



After edgerelaxation, our shortest path tree is-



Now, these sets are updated as-

Unvisited set: {b,c,e}

Visited set: {s,a,d}

Step-06:

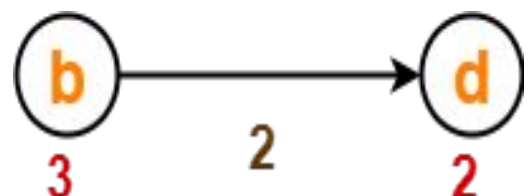
Vertex 'b' is chosen.

This is because shortest path estimate for vertex 'b' is least.

Vertex 'c' may also be chosen since for both the vertices, shortest path estimate is least.

The outgoing edges of vertex 'b' are relaxed.

Before Edge Relaxation_



Now,

$$d[b]+2=3+2=5>2$$

∴Nochange

Afteredgerelaxation,ourshortestpathtreeremainssthesameas
inStep-05.Now,thesetsareupdatedas-

Unvisitedset: {c,e}

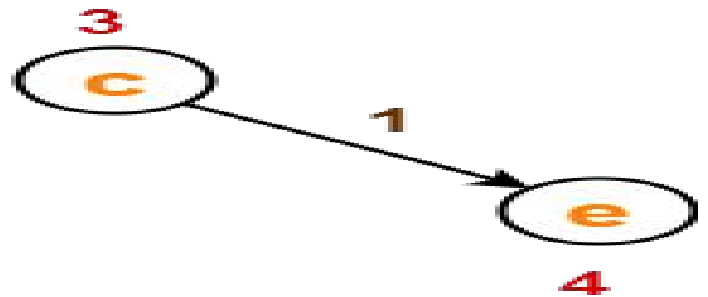
Visitedset: {S,a,d,b}

Step-07:

Vertex 'c' is chosen.

This is because shortest path estimate for vertex 'c' is least.

The outgoing edges of vertex 'c' are relaxed.

Before Edge Relaxation-

Now,

$$d[c] + 1 = 3 + 1 = 4 = 4$$

∴ No change

After edge relaxation, our shortest path tree remains the same as in Step-05. Now, these sets are updated as-

Unvisited set: {e}

Visited set: {S, a, d, b, c}

Step-08:

Vertex 'e' is chosen.

This is because shortest path estimate for vertex 'e' is least.

The outgoing edges of vertex 'e' are relaxed.

There are no outgoing edges for vertex 'e'.

So, our shortest path tree remains the same as in Step-05.

Now, these sets are updated as-

Unvisited set: { }

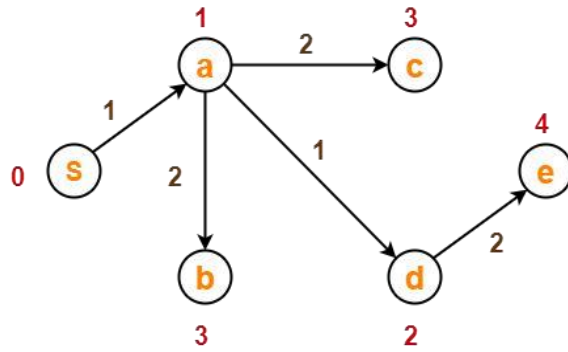
Visited set: {S, a, d, b, c, e}

Now,

All vertices of the graph are processed.

Our final shortest path tree is as shown below.

It represents the shortest path from source vertex 'S' to all other remaining vertices.



Shortest Path Tree

The order in which all the vertices are processed is:
S, a, d, b, c, e.

EXPERIMENT:-08

AIM: -

Study of Spanning trees and Kruskal's Algorithm

Software Used:-

MATLAB

Theory:-

Minimum Spanning Tree: Minimum spanning tree can be defined as the spanning tree in which the sum of the weights of the edge is minimum. The weight of the spanning tree is the sum of the weights given to the edges of the spanning tree.

An edge is a pair of vertices (u, v)

Total no. of trees = $(V)^{V-1}$

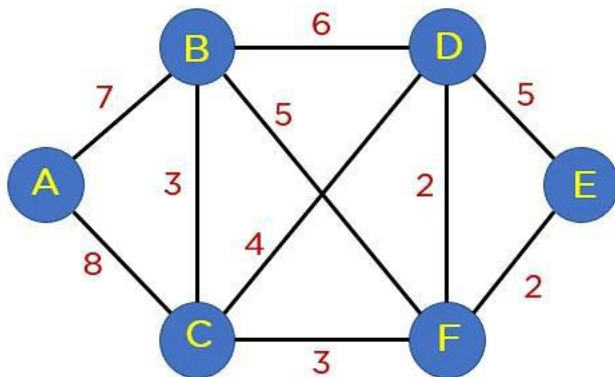
Number of edges = $V-1$

Kruskal Algorithm: Kruskal's algorithm to find the minimum cost spanning tree uses the greedy approach. This algorithm treats the graph as a forest and every node it has as an individual tree. A tree connects to another only and only if, it has the least cost among all available options and does not violate MST properties.

Steps for finding MST using Kruskal's Algorithm:

1. Sort all the edges in increasing order of their weight.
2. Pick the smallest edge. Check if it forms a cycle with the spanning tree formed so far. If cycle is not formed, include this edge. Else, discard it.
3. Repeat step#2 until there are $(V-1)$ edges in the spanning tree.

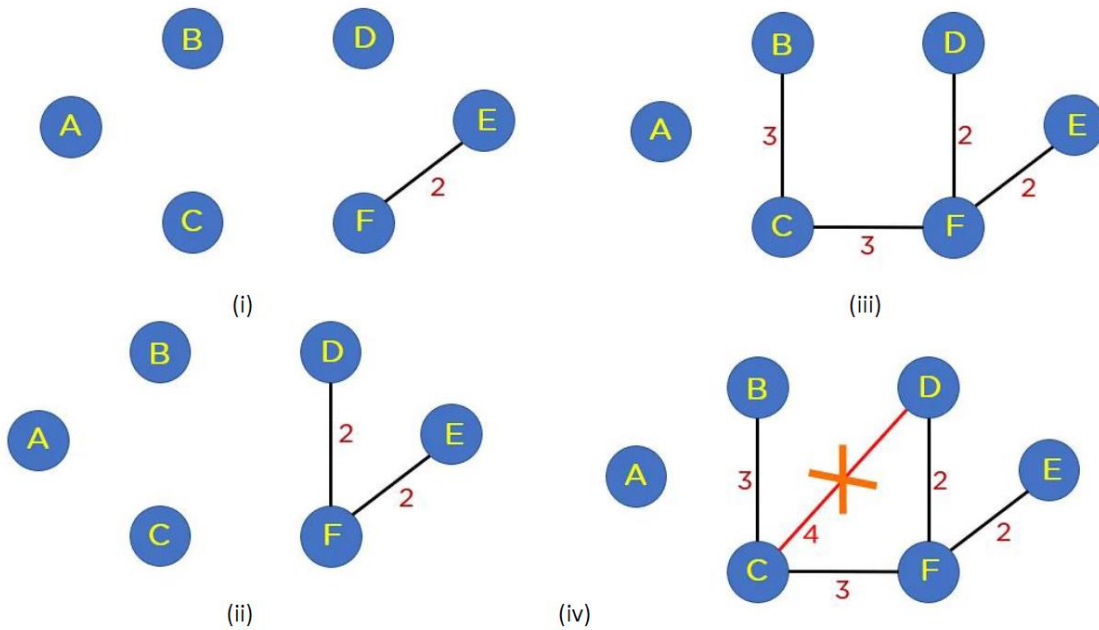
EXAMPLE 1

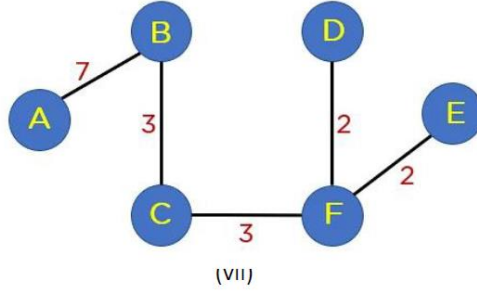
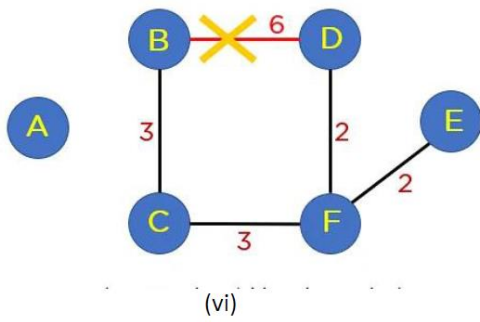
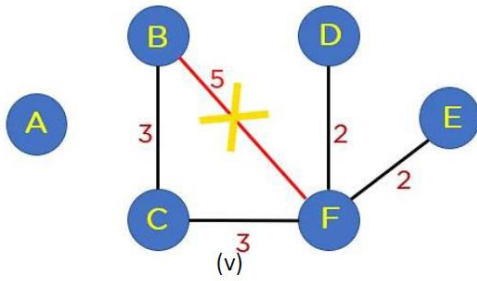


Total no. of vertices = 6

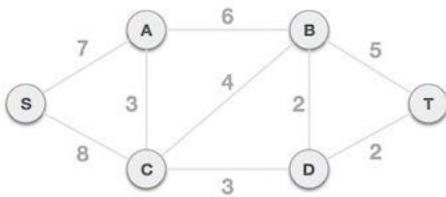
No. of edges in MST = 5

| Source Vertex(u) | Destination Vertex(v) | Edge Weight |
|------------------|-----------------------|-------------|
| E | F | 2 |
| F | D | 2 |
| B | C | 3 |
| C | F | 3 |
| C | D | 4 |
| B | F | 5 |
| B | D | 6 |
| A | B | 7 |
| A | C | 8 |





EXAMPLE 2:



Kruskal's algorithm –Pseudocode:

```

KRUSKAL(G):
A = ∅
For each vertex v ∈ G.V:
    MAKE-SET(v)
For each edge (u, v) ∈ G.E ordered by increasing order by weight(u, v):
    if FIND-SET(u) ≠ FIND-SET(v):
        A = A ∪ {(u, v)}
        UNION(u, v)
return A

```

Find & Union Operation

S={ 1, 2,3,4,5}

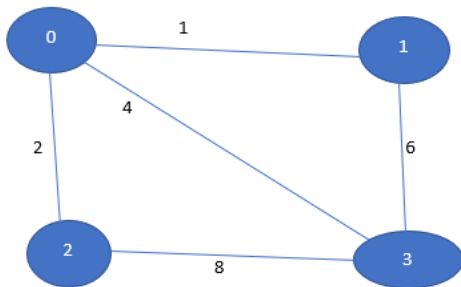
Disjoint set

S1={1,2} s2={3} s3={4} s4={5}

Find set(1)=s1, Find set(3)=s2 &

s1Us2={1,2,3}

EXAMPLE:



Line-1

A={ }

Line-2

V={0,1,2,3}

Line-3

{0} {1} {2} {3}

s1 s2 s3 s4

Line-4

| U | v | weight |
|---|---|--------|
| 0 | 1 | 1 |
| 0 | 2 | 2 |
| 0 | 3 | 4 |
| 1 | 3 | 6 |
| 2 | 3 | 8 |

0 1 1

0 2 2

0 3 4

1 3 6

2 3 8

Line-5 to 7

Find-set(0)=S1

Find-set(1)=S2

$\{0,1\} = S1$

$A=\{0-1, 0-2, 0-3,\}$

Find-set(0)=S1

Find-set(2)=S3

$\{0,1,2\}$

S1

Find-set(0)=S1

Find-set(3)=S4

$\{0,1,2,3\}$

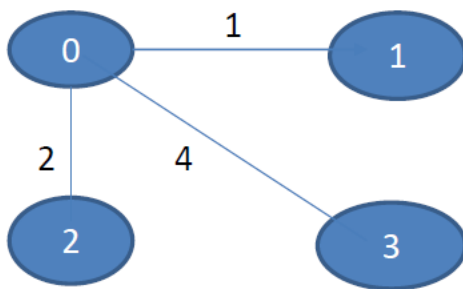
S1

Find-set(1)=S1 NOT CONSIDER

Find-set(3)=S1

Find-set(2)=S1 NOT CONSIDER

Find-set(3)=S1



MST = 7

Applications of MST:

1. In order to lay out electrical wiring
2. In computer network